

FIG

Presented at the FIG Working Week 2017  
May 29 - June 2, 2017 in Helsinki, Finland

FIG WORKING WEEK 2017

Helsinki Finland

29 May - 2 June 2017

# On the Use of Crustal Deformation Models in the Management of ETRS89 Realizations in Fennoscandia

Martin Lidberg, Jonas Ågren, Holger Steffen  
Lantmäteriet, Sweden

[Martin.Lidberg@lm.se](mailto:Martin.Lidberg@lm.se)

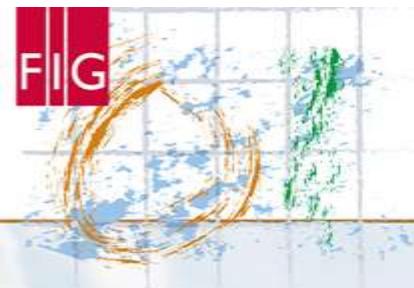
Surveying the world of tomorrow -  
From digitalisation to augmented reality

Organised by



Platinum Sponsors:





# FIG WORKING WEEK 2017

Surveying the world of tomorrow -

From digitalisation to augmented reality

Helsinki Finland 29 May - 2 June 2017

## Outline

- The Fennoscandia land uplift process
- What is ETRS89?
- Applying models of crustal deformations!
- The new model NKG2016LU
- Details on transformations
  - next talk by Pasi Häkli

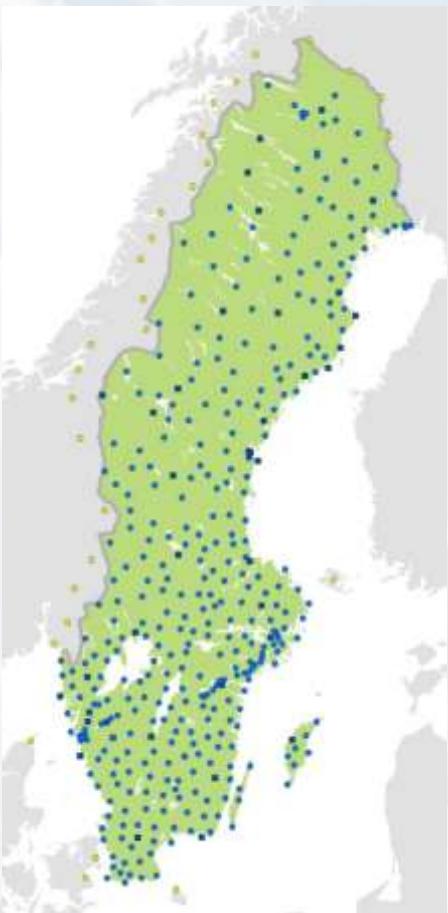
# FIG WORKING WEEK 2017

Surveying the world of tomorrow -

Helsinki Finland 29 May - 2 June 2017

From digitalisation to augmented reality

## Motivation – users asking for high performance in real time!

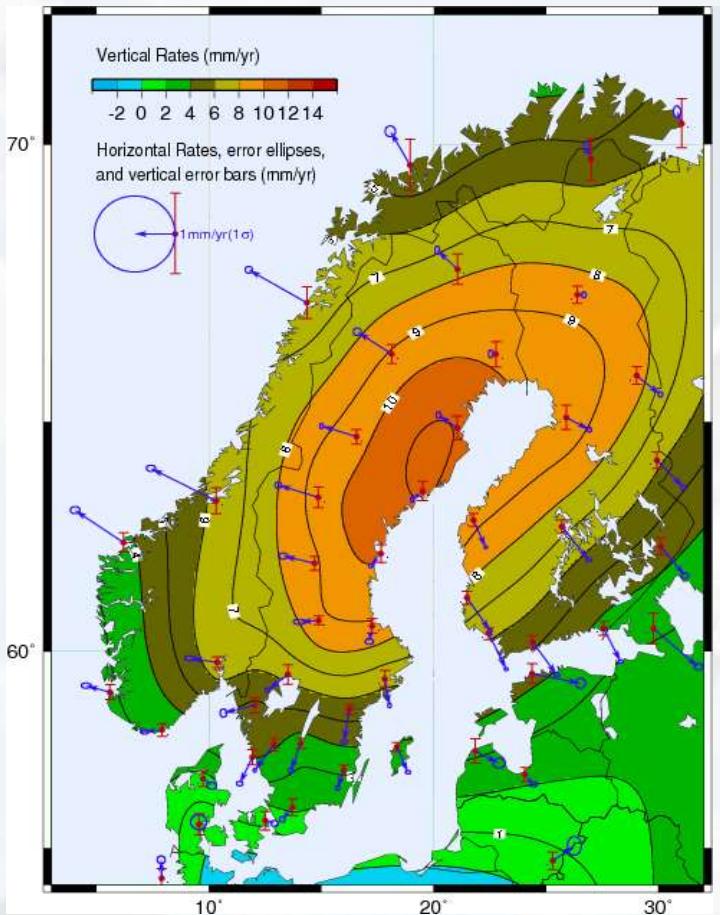


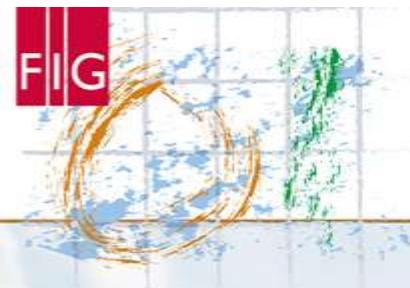
Surveying the world of tomorrow -

Helsinki Finland 29 May - 2 June 2017

From digitalisation to augmented reality

## The Fennoscandia Post Glacial Rebound, or GIA process!





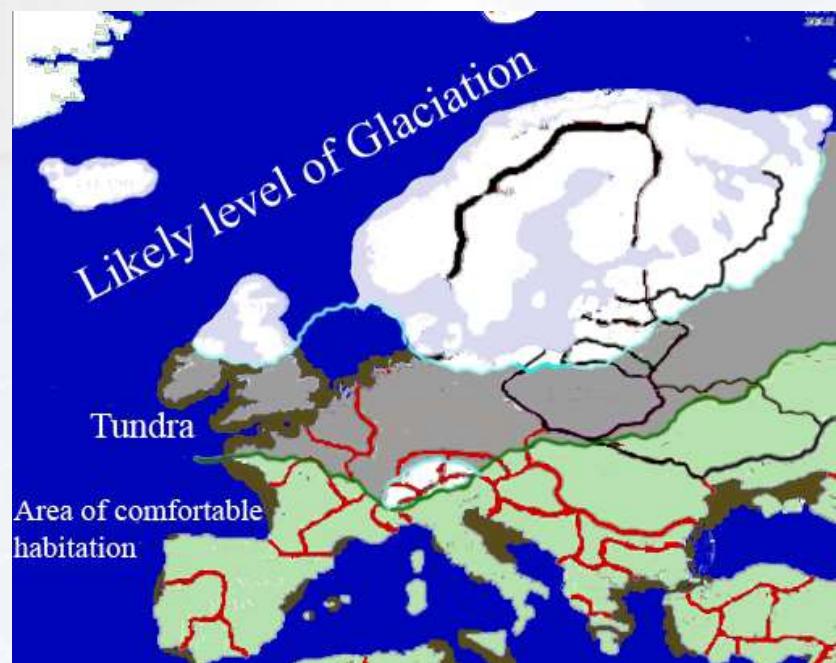
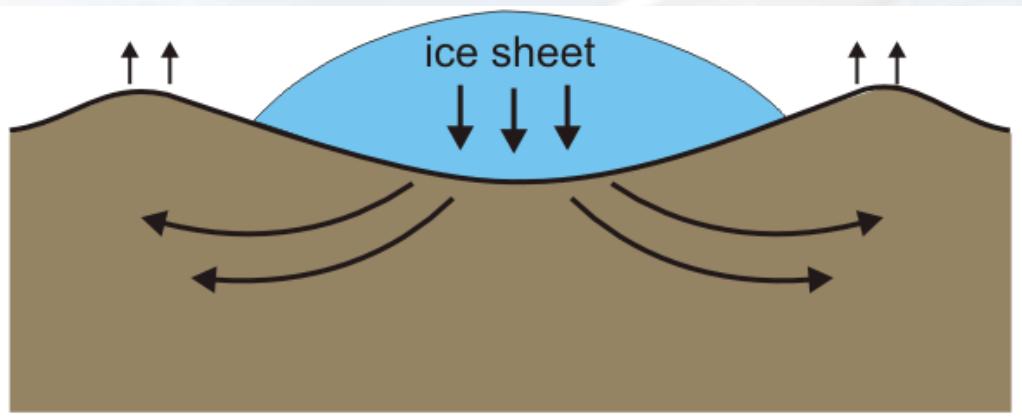
# FIG WORKING WEEK 2017

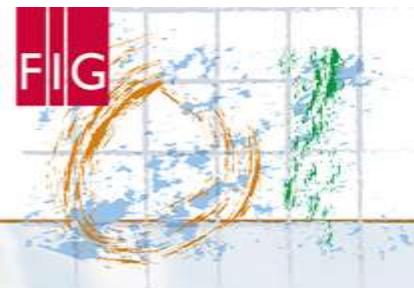
Surveying the world of tomorrow -

From digitalisation to augmented reality

Helsinki Finland 29 May - 2 June 2017

## The Glacial Isostatic Adjustment (GIA) phenomenon





# FIG WORKING WEEK 2017

Surveying the world of tomorrow -

Helsinki Finland 29 May - 2 June 2017

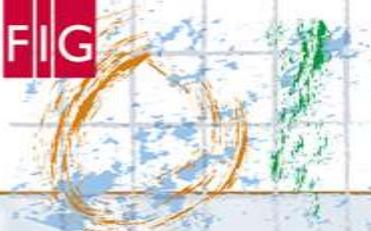
From digitalisation to augmented reality

## What is ETRS89?

- The European Terrestrial Reference System
- Coincident with ITRS at epoch 1989.0, and fixed to the stable part of the Eurasian tectonic plate.
- From Boucher&Altamimi (2011) Memo v8, chapter 3:

$$X^E(t_c) = X_{YY}^I(t_c) + T_{yy} + \begin{pmatrix} 0 & -\dot{R}3_{YY} & \dot{R}2_{YY} \\ \dot{R}3_{YY} & 0 & -\dot{R}1_{YY} \\ -\dot{R}2_{YY} & \dot{R}1_{YY} & 0 \end{pmatrix} \times X_{YY}^I(t_c) \cdot (t_c - 1989.0)$$

the plate motion model



# FIG WORKING WEEK 2017

Surveying the world of tomorrow -

Helsinki Finland 29 May - 2 June 2017

From digitalisation to augmented reality

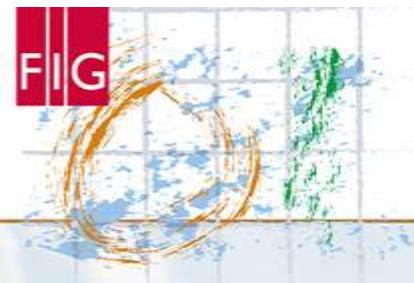
## Realizations of ETRS89 in Fennoscandia (the Nordic /Baltic countries)

Country	Name of realization	ETRF version	Realization epoch
Denmark	EUREF-DK94	ETRF92	1994.704
Estonia	EUREF-EST97	ETRF96	1997.56
Faroe Islands		ETRF2000	2008.75
Finland	EUREF-FIN	ETRF96	1997.0
Latvia	LKS-92	ETRF89	1992.75
Lithuania	EUREF-NKG-2003	ETRF2000	203.75
Norway	EUREF89	ETRF93	1995.0
Sweden	SWEREF 99	ETRF98	1999.5



Platinum Sponsors:





# FIG WORKING WEEK 2017

Surveying the world of tomorrow -

From digitalisation to augmented reality

Helsinki Finland 29 May - 2 June 2017

## To note:

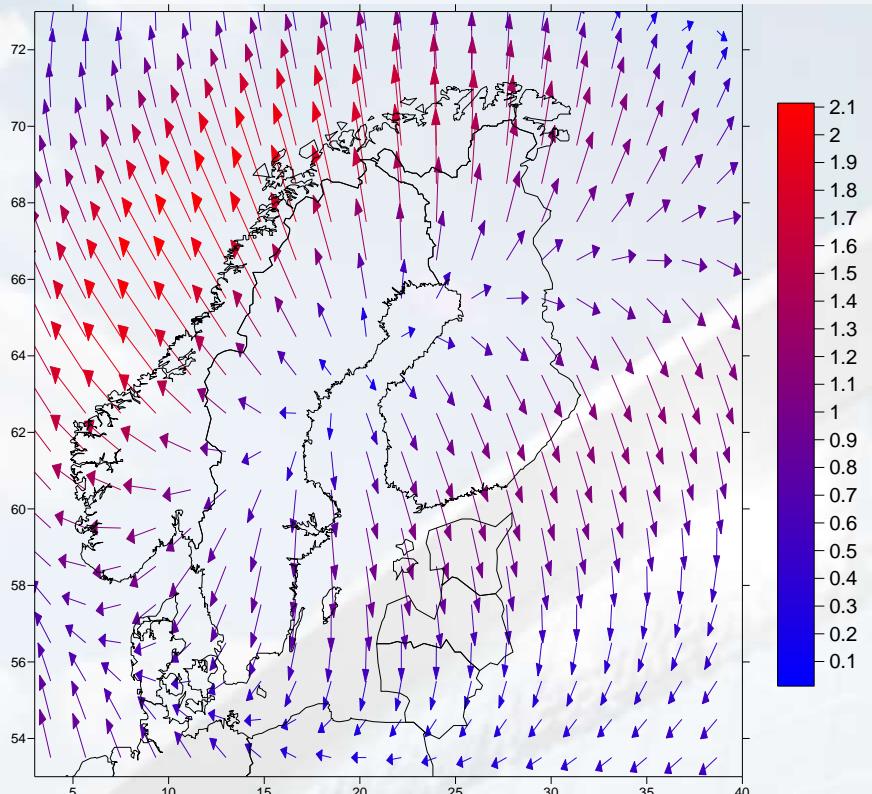
In presence of crustal deformations, the epoch is crucial.

Therefore:

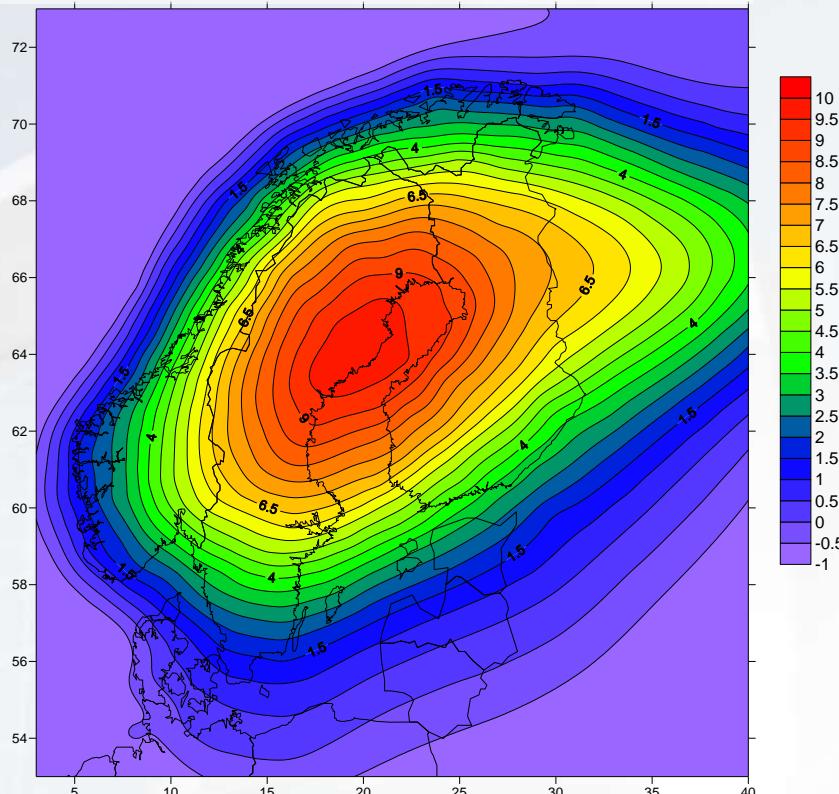
**Time tag everything!**



# The NKG\_RF2003\_vel velocity model



Horizontal (0 to 2 mm/yr):  
The GIA model in Milne 2001  
transformed to the GPS-  
velocities (in Lidberg 2007).



Vertical (-1 to 10 mm/yr):  
The NKG2005LU(ABS) model  
Based on: TG, repeated levelling,  
and GPS. (Ågren & Svensson 2006)

## Some formulas for the use of the model of crustal (intraplate) deformation

From velocities to coordinate differences

$$\begin{pmatrix} dX \\ dY \\ dZ \end{pmatrix} = (t_{\text{target epoch}} - t_{\text{observation epoch}}) \begin{pmatrix} V_{X_{\text{int ra}}} \\ V_{Y_{\text{int ra}}} \\ V_{Z_{\text{int ra}}} \end{pmatrix}_{NKG\_RF\,03vel}$$

From velocities in (n,e,u) to (X,Y,Z) frame

$$\begin{cases} \dot{X} = \frac{-Z}{R} \frac{X}{P} \dot{n} + \frac{-Y}{P} \dot{e} + \frac{X}{R} \dot{u} \\ \dot{Y} = \frac{-Z}{R} \frac{Y}{P} \dot{n} + \frac{X}{P} \dot{e} + \frac{Y}{R} \dot{u} \\ \dot{Z} = \frac{P}{R} \dot{n} + \frac{Z}{R} \dot{u} \end{cases}$$

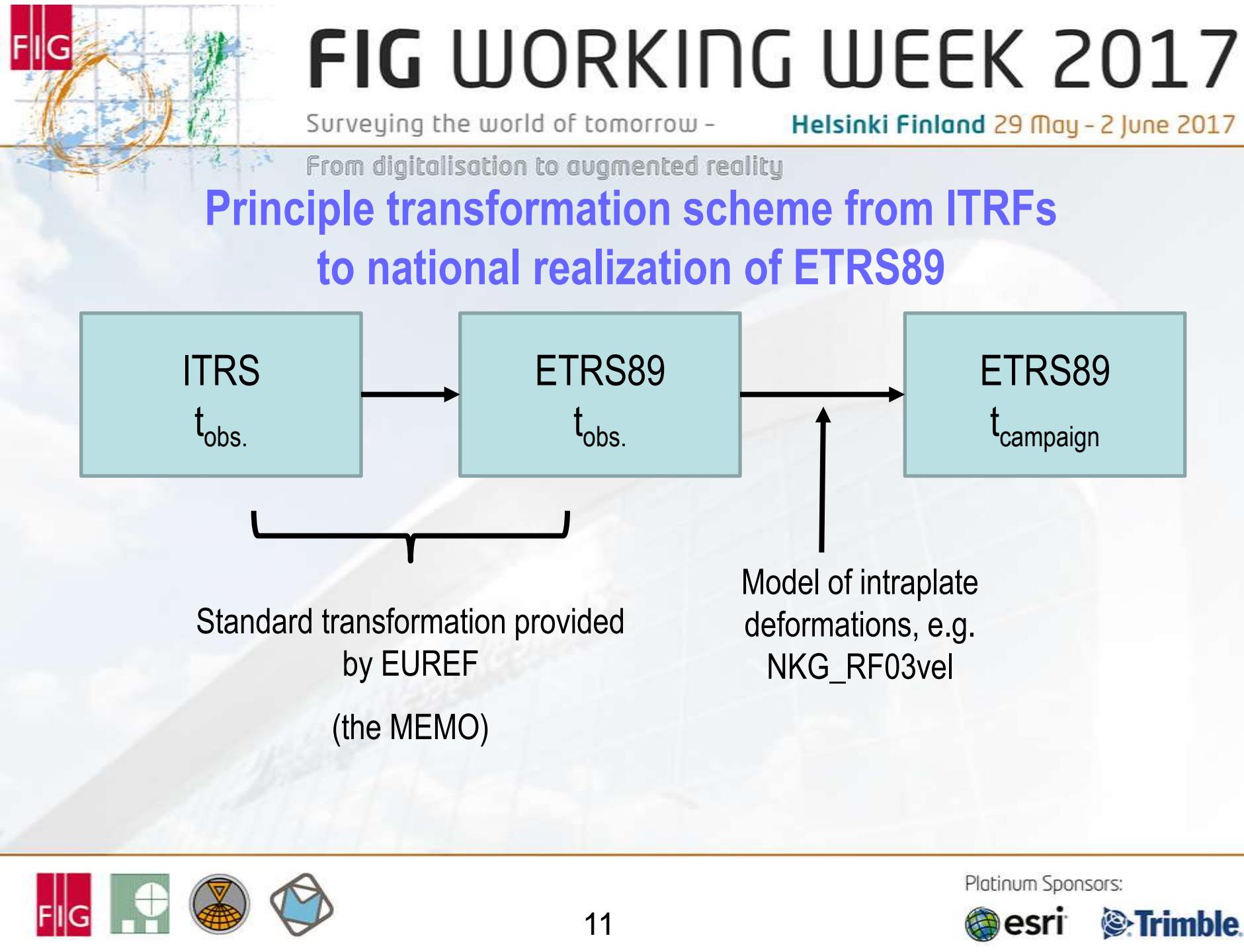
Where:

$$R = \sqrt{X^2 + Y^2 + Z^2}$$

And:

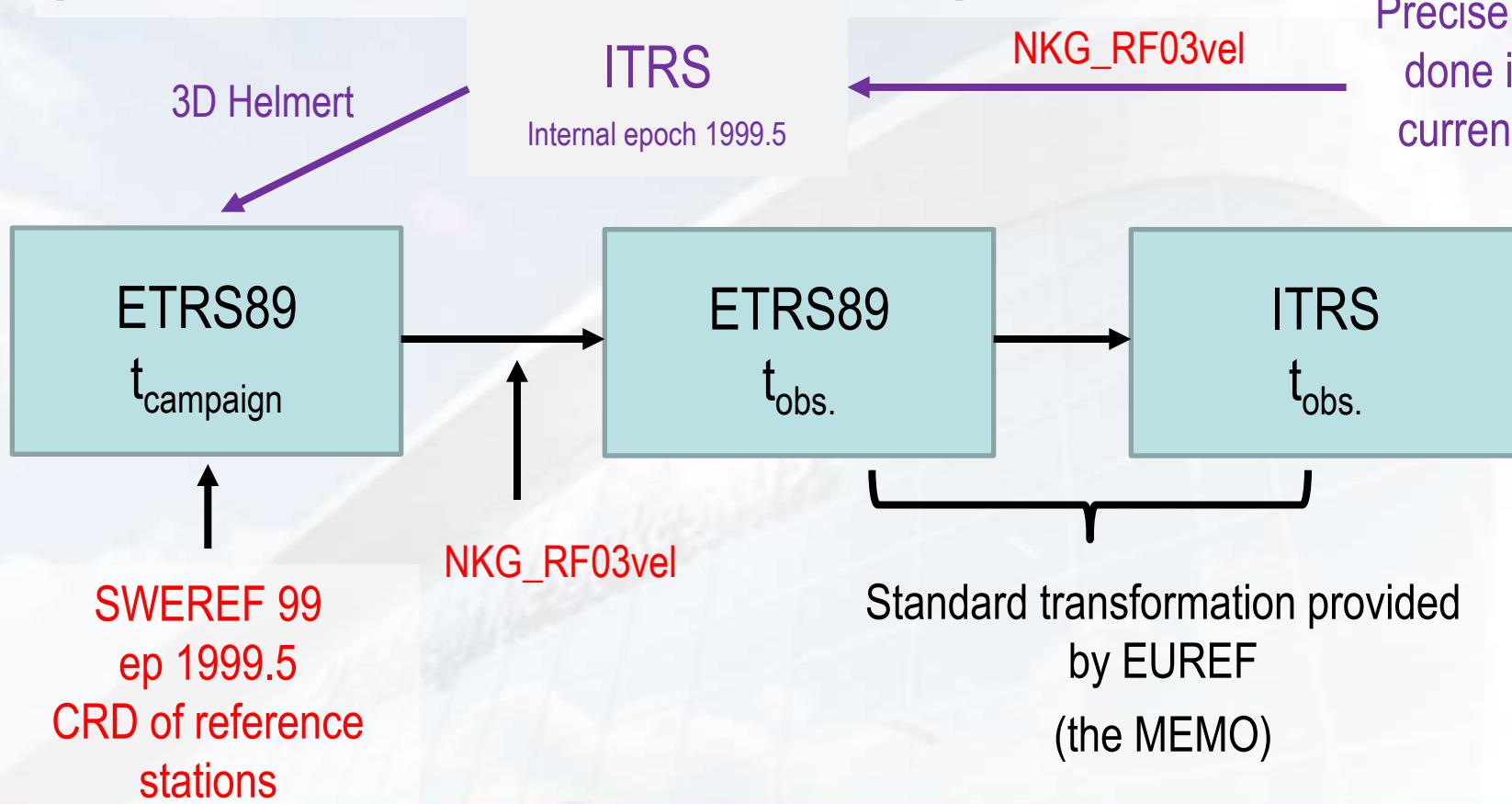
$$P = \sqrt{X^2 + Y^2}$$

(assuming a spherical earth)

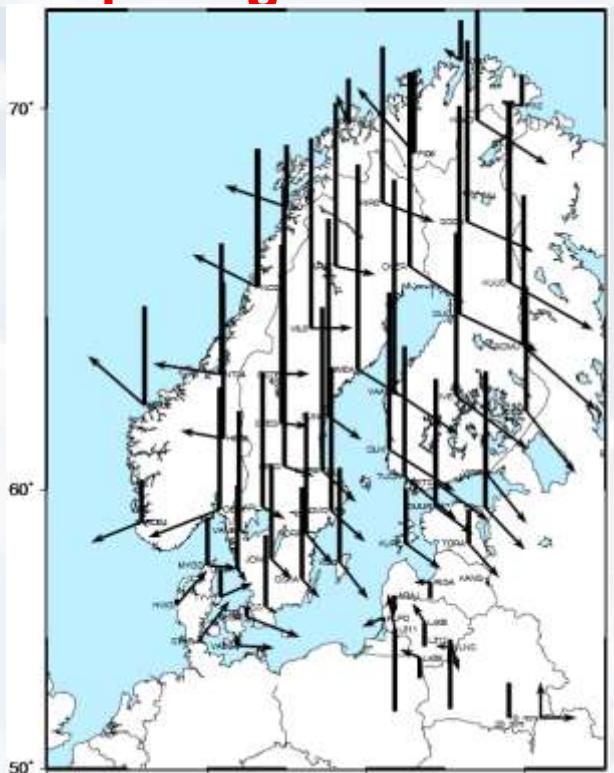


From digitalisation to augmented reality

## Practical transformation scheme while connecting to known permanent GNSS stations – example Sweden



## Comparing the national realizations of ETRS89 in Fennoscandia



Statistics:(n,e,u) in mm

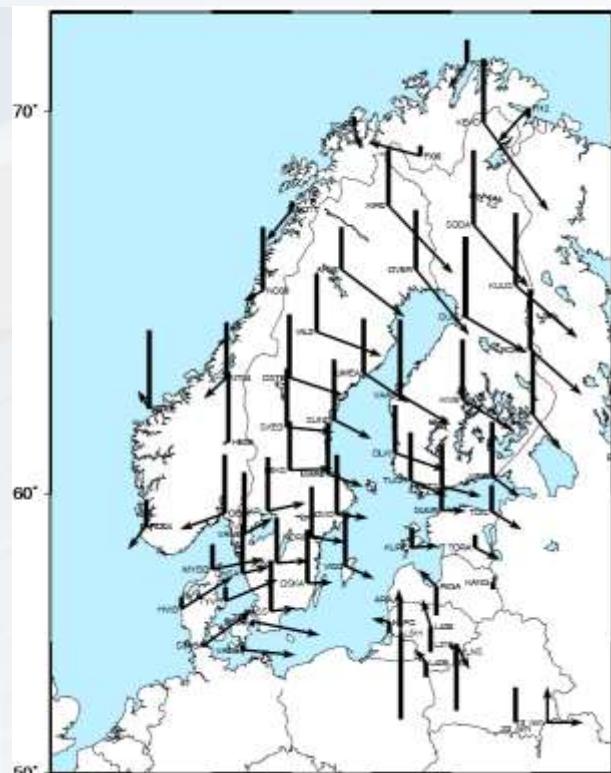
RMS	9	12	69
-----	---	----	----

Mean	-4	5	53
------	----	---	----

The NKG2008 campaign in ETRF2000 compared to national realizations.

**Left**, @ epoch 2008.75.

**Right**, @ epoch 2000.0, using a model for intraplate velocities (NKG\_RF03vel)



Statistics:(n,e,u) in mm

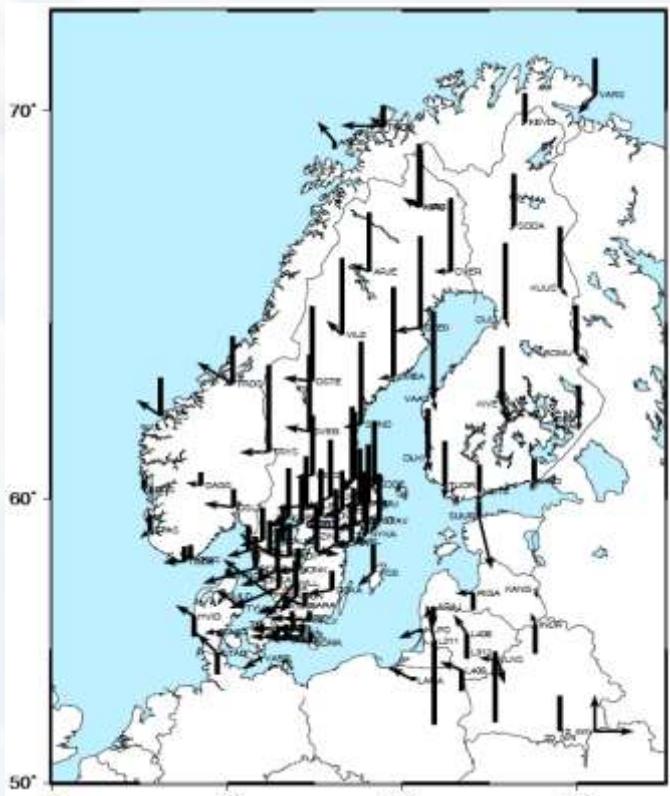
RMS	8	11	28
-----	---	----	----

Mean	-3	7	19
------	----	---	----

Platinum Sponsors:



Comparing the NKG2008, and the NKG2003 common campaigns. (ETRF2000)



Statistics:(n,e,u) in mm

RMS	4	5	24
-----	---	---	----

Mean	-5	-4	16
------	----	----	----

NKG2003 based  
on ITRF2000,  
NKG2008 based  
on ITRF2005.

**Left**, NKG2008  
@2008.75;  
NKG2003 @  
2003.75

**Right**, booth @  
epoch 2003.75,  
using the model  
NKG\_RF03vel

(No fit – just  
coordinate  
differences!)



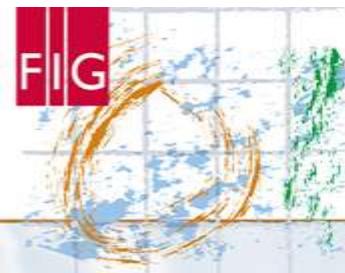
Statistics:(n,e,u) in mm

RMS	4	4	8
-----	---	---	---

Mean	0	-3	-3
------	---	----	----

Platinum Sponsors:





# FIG WORKING WEEK 2017

Surveying the world of tomorrow -

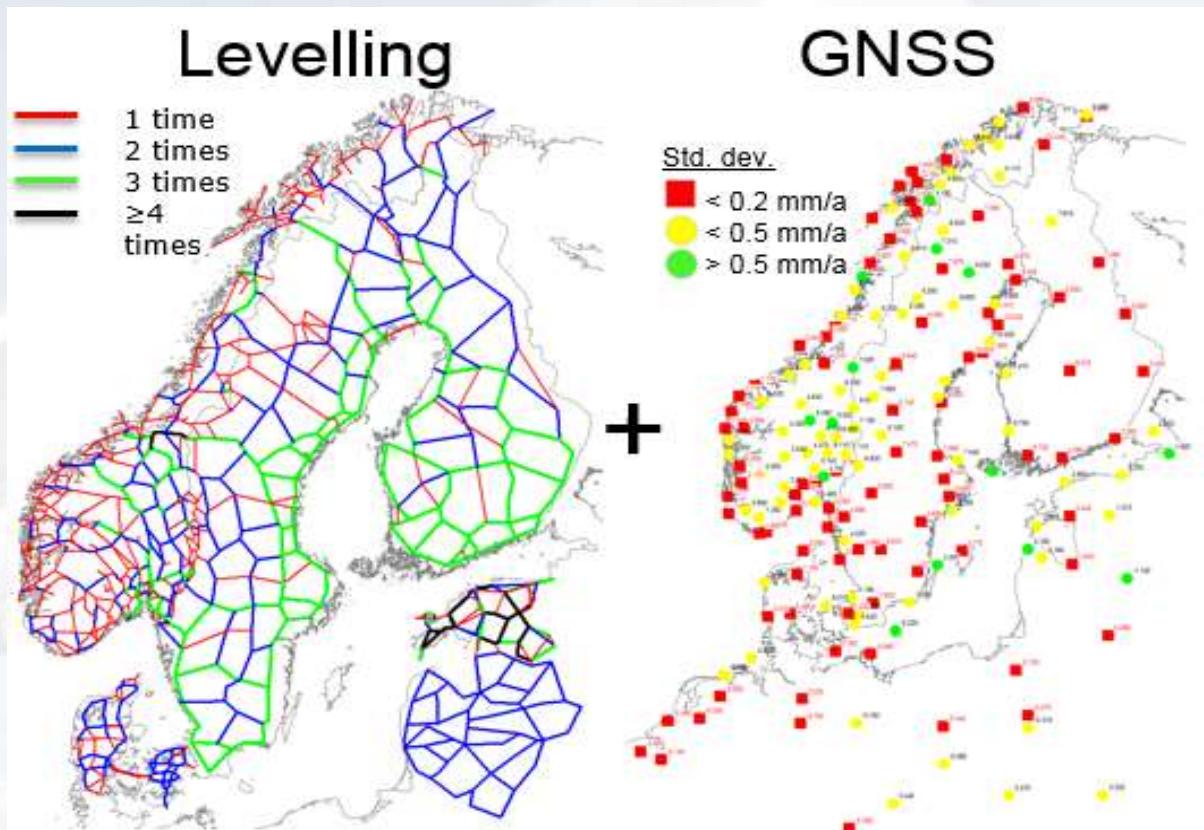
Helsinki Finland 29 May - 2 June 2017

From digitalisation to augmented reality

## Creating a new model for the Fennoscandia crustal deformations

### Input to the modelling

- Observations from repeated levelling
- 3D GPS velocities from the BIFROST project (10-15 year time series)
- Also a GIA-model
- But tide-gauge data is not used for the modelling!



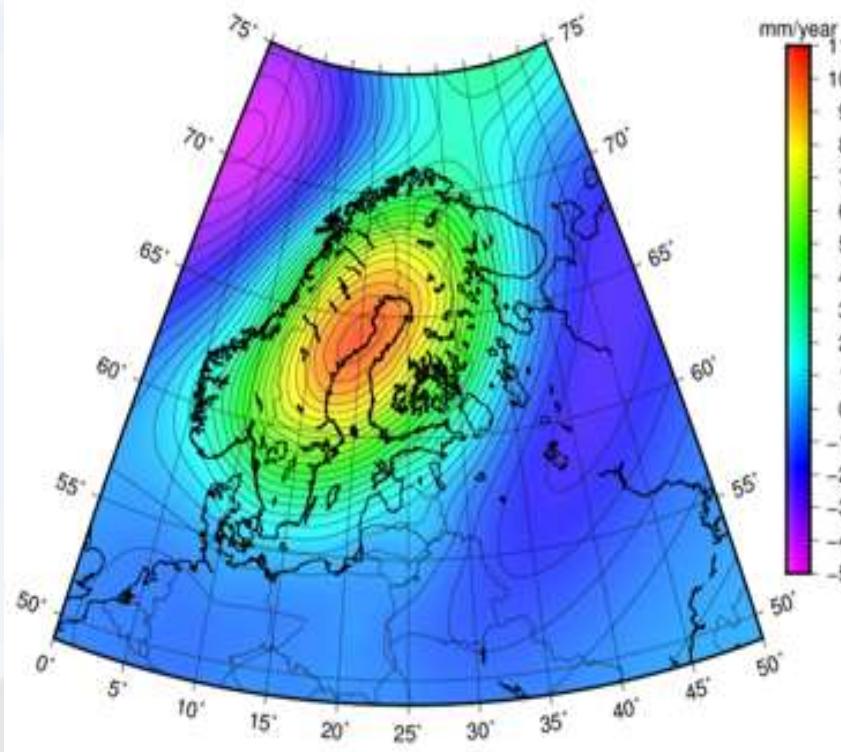
Surveying the world of tomorrow -

Helsinki Finland 29 May - 2 June 2017

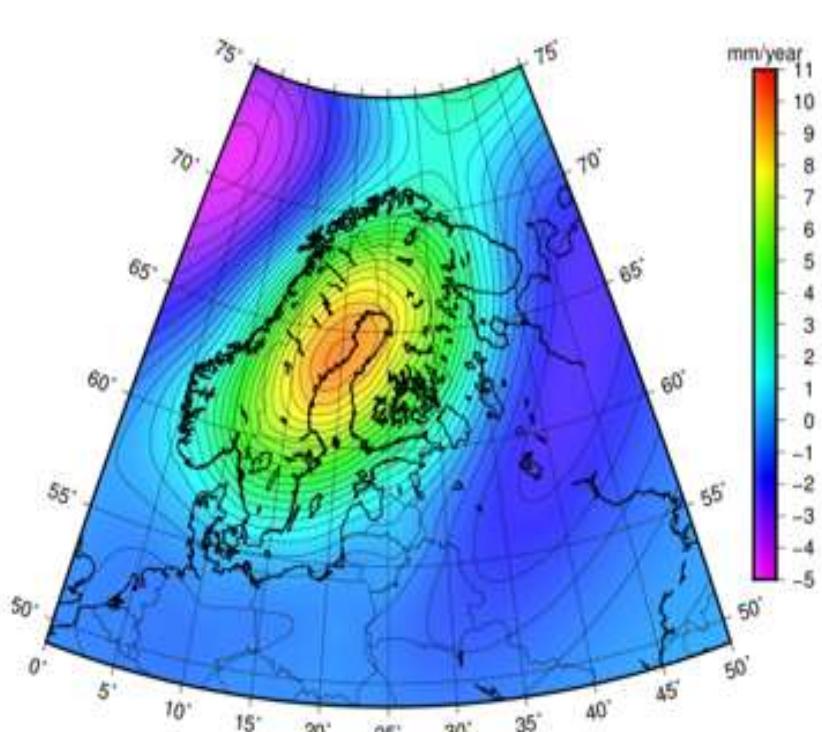
From digitalisation to augmented reality

## The semi-empirical land uplift model NKG2016LU\_abs/lev

NKG2016LU\_abs



NKG2016LU\_lev

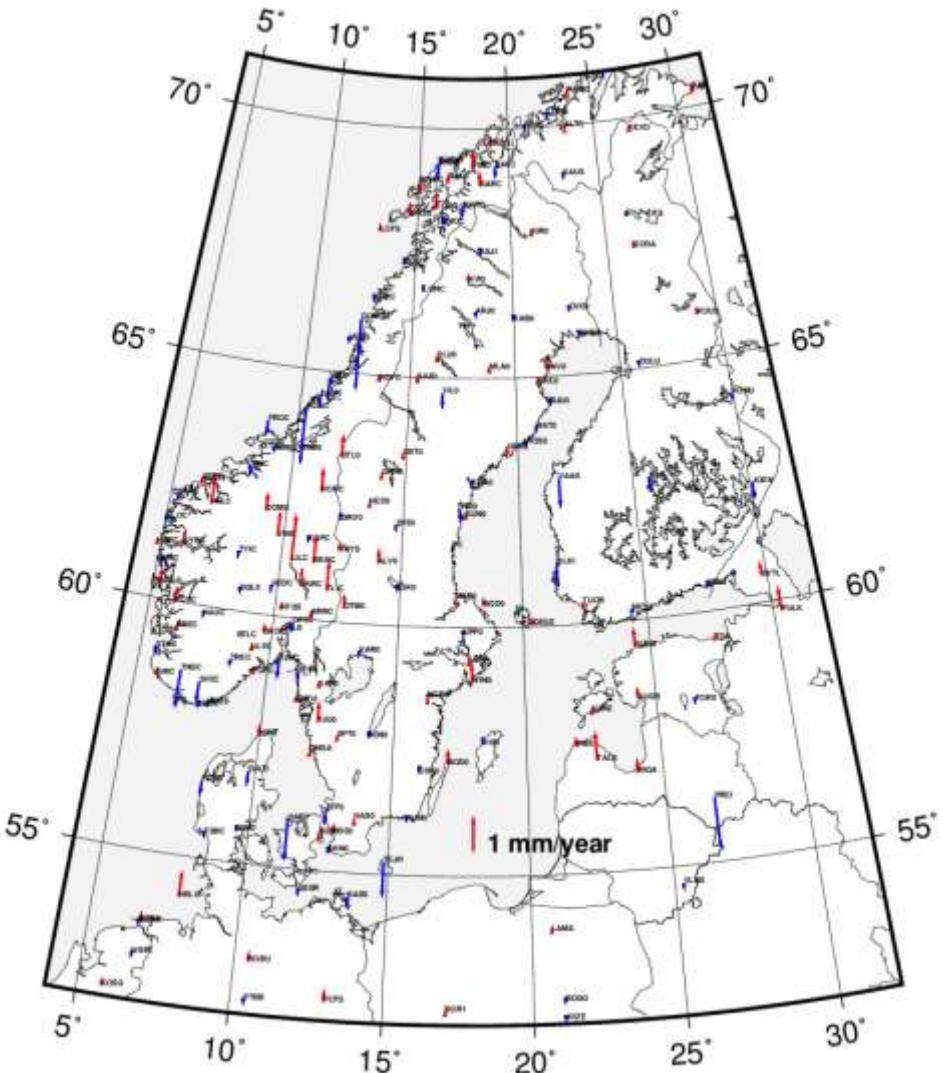


Surveying the world of tomorrow -

Helsinki Finland 29 May - 2 June 2017

From digitalisation to augmented reality

## Difference between BIFROST GNSS and NKG2016LU\_ABS



- Statistics (mm/year):

#	179
Min	-2.00
Max	1.32
Mean	0.02
StdDev	0.42

Platinum Sponsors:



## The horizontal velocity model

GPS velocities minus GIA model  
“best sites”:

(0.4, 0.2, 0.4) (n,e,u) mm/yr std.  
*(after 6-par fit, applying rotation and  
translation rates)*

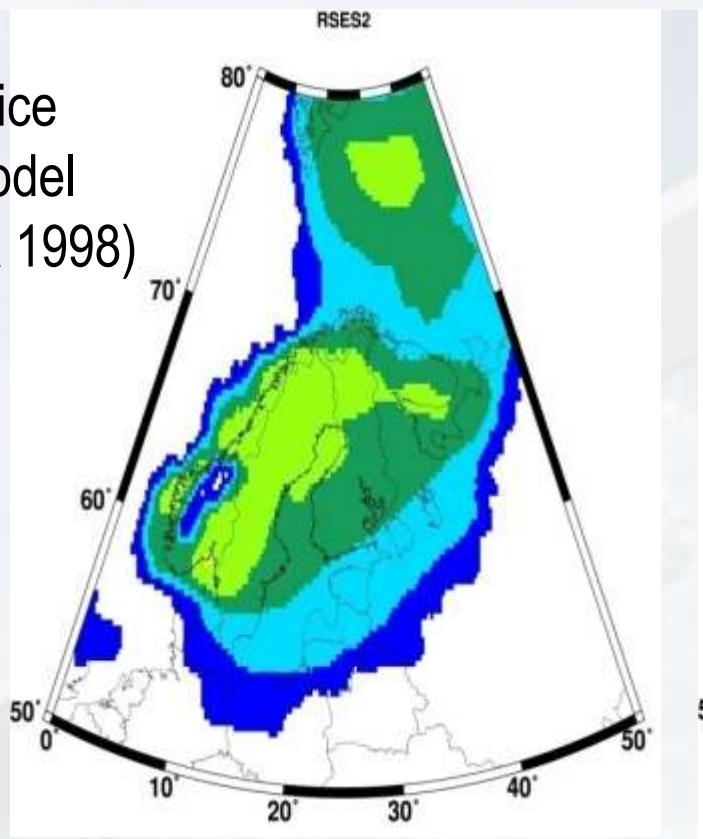
Note the systematic differences  
in the North direction



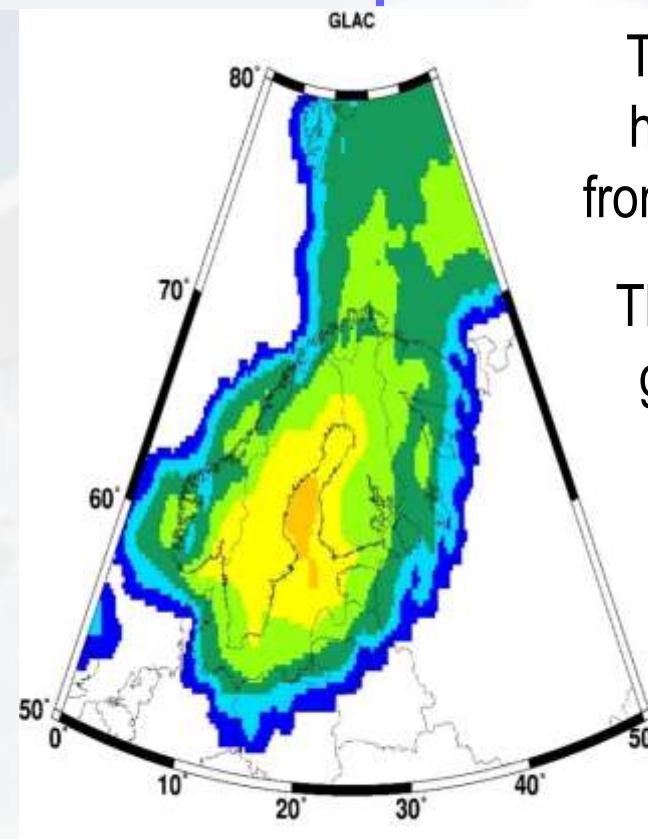
## Developments in GIA modelling:

### New Thermo-mechanical ice model examples at LGM

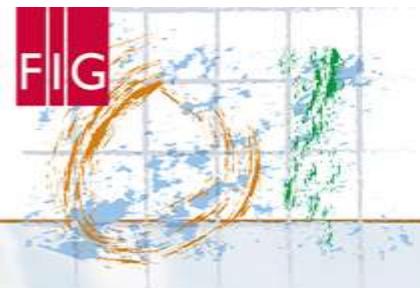
The "old" ice history model  
(Lambeck 1998)



The "new" ice history model  
from Lev Tarasov.



The ice history governed by models for climate and glaciology.



# FIG WORKING WEEK 2017

Surveying the world of tomorrow -

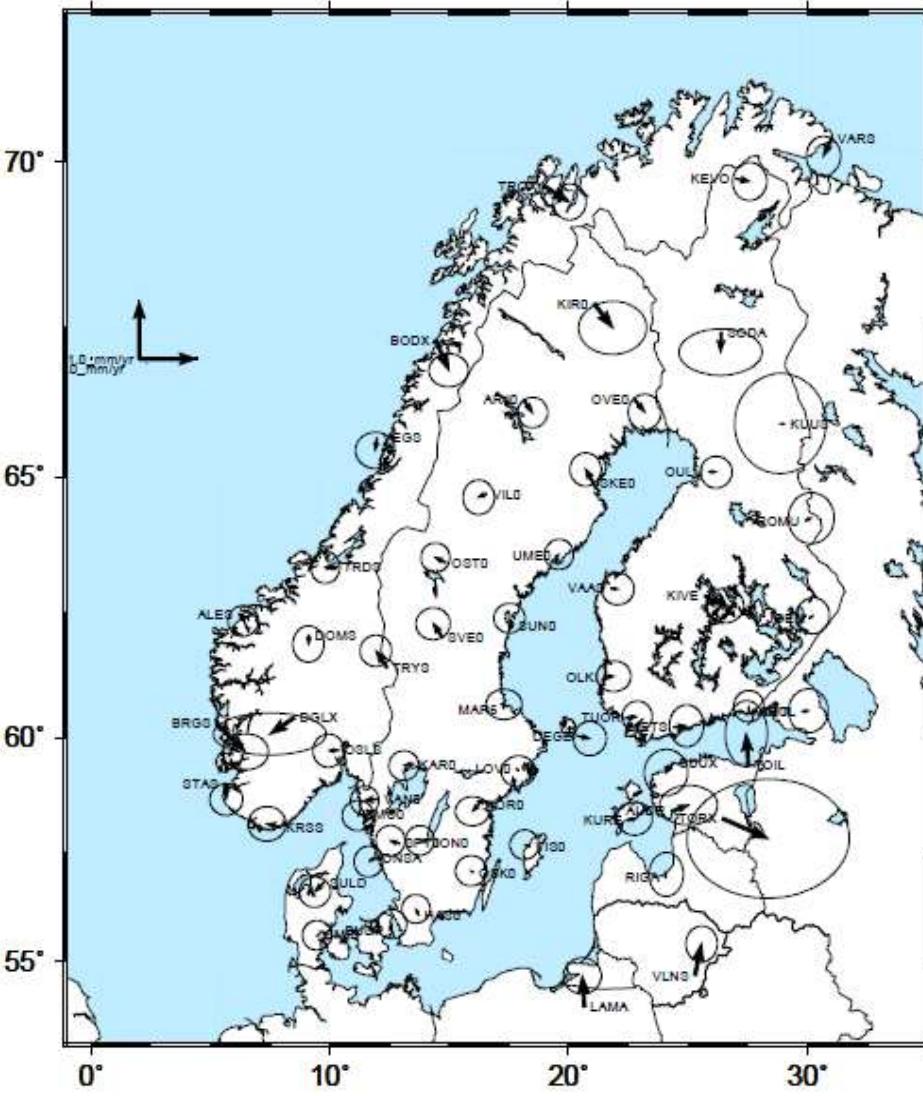
From digitalisation to augme

Helsinki Finland 29 May - 2 June 2017

## New GIA model rotated to the GPS velocities (in ETRS89)

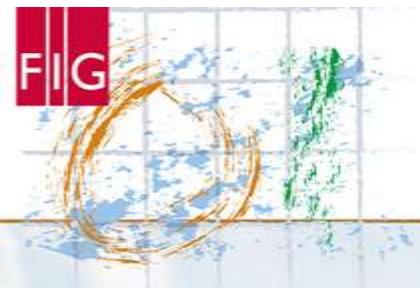
Using 66 well defined GPS sites

RMS: 0.2 mm/year in north and east



Platinum Sponsors:





# FIG WORKING WEEK 2017

Surveying the world of tomorrow -

From digitalisation to augmented reality

Helsinki Finland 29 May - 2 June 2017

## Outline

- The Fennoscandia land uplift process
- What is ETRS89?
- Applying models of crustal deformations!
- The new model NKG2016EU
- Details on transformations  
→ next talk by Pasi Häkli

Discussion?!